## Applications, properties and curiosities of the WRP and related problems

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## OUTLINE:

(1) From Shortest Paths in Graphs to Geometric Shortest Paths
(2) The Weightred Region Problem (WRP)

- Applications
- Properties
- Curiosities
(3) The Simple-Path $\ell_{p}$-WRP
- Local optimality condition for gate points and relation with Snell's law


## Shortest Path Problem



El camino más corto que lleva del nodo 1 al 7 es
$1 \longrightarrow 3 \longrightarrow 6 \longrightarrow 7$ y su longitud es 4 .

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## Geometric Shortest Path Problems

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## Geometric Shortest Path Problems



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## Geometric Shortest Path Problems



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## Geometric Shortest Path Problems



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## Weighted Region Problem (WRP)



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## Weighted Region Problem (WRP)



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## WRP and triangle inequality



$$
\begin{aligned}
& 3\|(10,9)-(1,0)\|_{2}=38.1837 \ldots \\
& 3\|(1,1)-(1,0)\|_{2}+2\|(1,6)-(1,1)\|_{2}+\|(1,9)-(1,6)\|_{2}=16 \\
& \|(4,9)-(1,9)\|_{2}+2\|(9,9)-(4,9)\|_{2}+3\|(10,9)-(9,9)\|_{2}=16
\end{aligned}
$$

## Applications of the WRP



Figure: Mitchell and Papadimitriou (1991)

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## Applications of the WRP



Figure: Gheibi, Maheshwari, Sack and Scheffer (2018)

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## Local optimality condition for gate points



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## Local optimality condition for gate points



## Snell's law



## Snell's law



$$
n_{1} \sin \theta_{1}=n_{2} \sin \theta_{2}
$$

## Some references on the WRP and related problems

- J.S.B. Mitchell, C.H. Papadimitriou: The weighted region problem: finding shortest paths through a weighted planar subdivision. J. Assoc. Comput. Mach. 38, 18-73 (1991)
- C. S. Mata, J.S.B. Mitchell: A new algorithm for computing shortest paths in weighted planar subdivisions. In Proceedings of the thirteenth annual symposium on Computational geometry, 264-273 (1997)
- L. Aleksandrov, A. Maheshwari, J.-R. Sack: Determining approximate shortest paths on weighted polyhedral surfaces. J. Assoc. Comput. Mach., 25-53 (2005)
- Z. Sun, J. Reif: On finding approximate optimal paths in weighted regions. J. Algorithms 58, 1-32 (2006)
- S.-W. Cheng, H.-S. Na, A. Vigneron, Y. Wang: Approximate shortest paths in anisotropic regions. SIAM J. Comput. 38, 802-824, (2008)
- S.-W. Cheng, H.-S. Na, A. Vigneron, Y. Wang: Querying approximate shortest paths in anisotropic regions. SIAM J. Comput. 39, 1888-1918 (2010)
- M. Fort, J.A. Sellares: Approximating generalized distance functions on weighted triangulated surfaces with applications. J. Comput. Appl. Math. 236, 3461-3477 (2012)
- A. Gheibi, A. Maheshwari, J. R. Sack, C. Scheffer: Path refinement in weighted regions. Algorithmica, 80(12), 3766-3802 (2018)


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## Unsolvability of the WRP

## De Carufel, Grimm, Maheshwari, Owen and Smid (2014)

In general, the exact solution of WRP cannot be computed in $\mathbb{Q}$ using a finite number of the operations,$+-\times, \div, \sqrt[k]{ }$, for any $k \geq 2$.

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In general, the exact solution of WRP cannot be computed in $\mathbb{Q}$ using a finite number of the operations,$+-\times, \div \sqrt[k]{ }$, for any $k \geq 2$.

Gheibi, Maheshwari, Sack and Scheffer (2018):

- "It is unlikely that WRP can be solved in polynomial time".
- "To the best of our knowledge, still no FPTAS is known for WRP".

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## Counterexample in De Carufel, Grimm, Maheshwari, Owen and Smid (2014)



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## Counterexample in De Carufel, Grimm, Maheshwari, Owen and Smid (2014)

For simplicity, we let $\theta=\theta_{1}$. Hence, we must have $\sin \left(\theta_{2}\right)=\frac{w_{1}}{w_{2}} \sin (\theta)$ and $\sin \left(\theta_{3}\right)=\frac{w_{1}}{w_{3}} \sin (\theta)$.
Since the sum of the vertical distances travelled in all regions must be equal to the $y$-coordinate of $t$, we need to solve

$$
\tan (\theta)+2 \tan \left(\theta_{2}\right)+3 \tan \left(\theta_{3}\right)=2
$$

Since $\tan (\theta)=\frac{\sin (\theta)}{\sqrt{1-\sin ^{2}(\theta)}}$ for $0 \leqslant \theta<\frac{1}{2} \pi$, this can be rewritten as

$$
\phi(X)=\frac{X}{\sqrt{1-X^{2}}}+2 \frac{\frac{w_{1}}{w_{2}} X}{\sqrt{1-\left(\frac{w_{1}}{w_{2}} X\right)^{2}}}+3 \frac{\frac{w_{1}}{w_{3}} X}{\sqrt{1-\left(\frac{w_{1}}{w_{3}} X\right)^{2}}}=2
$$

where $X=\sin (\theta)$. By appropriately squaring three times, this can be transformed into

$$
\begin{aligned}
p_{12}(u)= & 419904-3545856 u+12394944 u^{2}-24006816 u^{3}+28904608 u^{4}-22882588 u^{5} \\
& +12204109 u^{6}-4396586 u^{7}+1060979 u^{8}-168272 u^{9}+16843 u^{10}-970 u^{11}+25 u^{12}=0
\end{aligned}
$$

where $u=X^{2}$.

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## Simple-Path $\ell_{p}$-WRP



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## Balls of the $\ell_{p}$-norms

$$
\|x\|_{p}=\left(\sum_{i=1}^{n}\left|x_{i}\right|^{p}\right)^{\frac{1}{p}} \quad \forall x \in \mathbb{R}^{n} \quad \text { where } p \in[1, \infty)
$$



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## Balls of the "pasted" $\ell_{p}$-norms



Figure: Plastria (2019)

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## Blanco, Puerto and Ponce (2017)



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## Simple-Path $\ell_{p}$-Weighted-Region Location Problem



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## Classical Snell's law

## Snell's law - Classical form <br> $$
w_{A} \sin \theta(c-a, v)=w_{B} \sin \theta(b-c, v)
$$

for all non-zero vector $v \perp H$.

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## Snell's law - Cosine form

$$
w_{A} \cos \theta(c-a, v)=w_{B} \cos \theta(b-c, v)
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for all non-zero vector $v \in V(H)$.

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for all non-zero vector $v \in V(H)$.

## Snell's law - Dot product form

$w_{A}\left(\frac{c-a}{\|c-a\|_{2}}\right)^{T} v=w_{B}\left(\frac{b-c}{\|b-c\|_{2}}\right)^{T} v$
for all non-zero vector $v \in V(H)$.

## Generalized Snell's law

## Optimality condition for the gate point $c$

$$
w_{A} u_{A}^{T} v=w_{B} u_{B}^{T} v
$$

for all non-zero vector $v \in V(H)$, where

$$
\begin{gathered}
u_{A}=\left(\left[\frac{\left|c_{1}-a_{1}\right|}{\|c-a\|_{p_{A}}}\right]^{p_{A}-1} \operatorname{sign}\left(c_{1}-a_{1}\right)\right. \\
\left.\ldots,\left[\frac{\left|c_{n}-a_{n}\right|}{\|c-a\|_{p_{A}}}\right]^{p_{A}-1} \operatorname{sign}\left(c_{n}-a_{n}\right)\right)^{T}
\end{gathered}
$$

and

$$
\begin{aligned}
& u_{B}=\left(\left[\frac{\left|b_{1}-c_{1}\right|}{\|b-c\|_{p_{B}}}\right]^{p_{B}-1} \operatorname{sign}\left(b_{1}-c_{1}\right)\right. \\
& \left.\ldots,\left[\frac{\left|b_{n}-c_{n}\right|}{\|b-c\|_{p_{B}}}\right]^{p_{B}-1} \operatorname{sign}\left(b_{n}-c_{n}\right)\right)^{T}
\end{aligned}
$$

# Advances on data analysis, logistics and transportation problems on complex networks 

## Blanco, Puerto and Ponce (2017)



$$
\sin _{p_{A}} \gamma_{a}=\frac{\left|\alpha^{t} a-\beta\right|}{\left\|a-x^{*}\right\|_{p_{A}}} \quad\left(\text { analogously } \sin _{p_{B}} \gamma_{b}=\frac{\left|\alpha^{t} b-\beta\right|}{\left\|b-x^{*}\right\|_{p_{B}}}\right)
$$

## Polarity correspondence of $\ell_{p}$-norms

## Definition (Polar norm)

Consider an $\ell_{p}$-norm with $p \in(1,+\infty)$ and let $B_{p}$ be its unit ball. Then, there exists a unique $\ell_{p^{\circ}}$-norm with $p^{\circ} \in(1,+\infty)$ whose unit ball $B_{p^{\circ}}$ is the polar set of $B_{p}$, where the polar set $B_{p}^{\circ}$ of $B_{p}$ is given by

$$
B_{p}^{\circ}=\left\{x^{\prime} \in \mathbb{R}^{n}: x^{T} x^{\prime} \leq 1, \forall x \in B_{p}\right\} .
$$

The norm $\ell_{p^{\circ}}$ is called the polar norm of $\ell_{p}$.

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## Proposition (Characterization of polarity correspondence)

The norms $\ell_{p}$ and $\ell_{p^{\circ}}$ are polar to each other iff $\frac{1}{p}+\frac{1}{p^{\circ}}=1$.

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## Proposition (Characterization of polarity correspondence)

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Notation:


## Some considerations

- The standard angle between two non-zero vectors $v$ and $v^{\prime}$ is defined as the real number $\theta \in[0, \pi]$ satisfying the equality $\cos \theta=\frac{v^{T} v^{\prime}}{\|v\|_{2}\left\|v^{\prime}\right\|_{2}}$.


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- It is the Cauchy-Schwarz inequality $\left|v^{T} v^{\prime}\right| \leq\|v\|_{2}\left\|v^{\prime}\right\|_{2}$ which ensures $-1 \leq \frac{v^{T} v^{\prime}}{\|v\|_{2}\left\|v^{\prime}\right\|_{2}} \leq 1$ (proper image of the cosine function).


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- More generally, recall that in all normed spaces $\left(\mathbb{R}^{n},\|\cdot\|\right)$ where the norm $\|\cdot\|$ can be defined from an inner product $\langle\cdot, \cdot\rangle$ as $\|\tilde{v}\|=\sqrt{\langle\tilde{v}, \tilde{v}\rangle}$ for each $\tilde{v} \in \mathbb{R}^{n}$, the Cauchy-Schwarz inequality $\left|\left\langle v, v^{\prime}\right\rangle\right| \leq\|v\|\left\|v^{\prime}\right\|$ is satisfied.


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- Consider now a normed space $\left(\mathbb{R}^{n},\|\cdot\|_{p}\right)$ with $p \in(1,+\infty)$. It is known that when $p \neq 2$ there is not an inner product $\langle\cdot, \cdot\rangle$ from which the norm $\|\cdot\|_{p}$ can be defined as indicated above. Moreover, the Cauchy-Schwarz inequality is not satisfied in $\left(\mathbb{R}^{n},\|\cdot\|_{p}\right)$ when $p \neq 2$.


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- The standard angle between two non-zero vectors $v$ and $v^{\prime}$ is defined as the real number $\theta \in[0, \pi]$ satisfying the equality $\cos \theta=\frac{v^{T} v^{\prime}}{\|v\|_{2}\left\|v^{\prime}\right\|_{2}}$.
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- Hölder inequality states:

$$
\sum_{k=1}^{n}\left|v_{k} v_{k}^{\prime}\right| \leq\|v\|_{p}\left\|v^{\prime}\right\|_{p^{\circ}}
$$

for all $v=\left(v_{1}, \cdots, v_{n}\right)^{T}, v^{\prime}=\left(v_{1}^{\prime}, \cdots, v_{n}^{\prime}\right)^{T} \in \mathbb{R}^{n}$. Hölder inequality ensures $-1 \leq \frac{v^{T} v^{\prime}}{\|v\|_{p}\left\|v^{\prime}\right\|_{p^{\circ}}} \leq 1$ for all non-zero vectors $v, v^{\prime} \in \mathbb{R}^{n}$.

## Polar vector

## Definition ( $\ell_{p}$-angle)

Let $p \in(1,+\infty)$. Given two non-zero vectors $v, v^{\prime} \in \mathbb{R}^{n}$, the $\ell_{p}$-angle between $v$ and $v^{\prime}$, which we denote by $\theta_{p}\left(v, v^{\prime}\right)$, is the real number $\theta_{p}\left(v, v^{\prime}\right) \in[0, \pi]$ such that $\cos \theta_{p}\left(v, v^{\prime}\right)=\frac{v^{T} v^{\prime}}{\|v\|_{p}\left\|v^{\prime}\right\|_{p^{\circ}}}$.

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Remark: When $p \neq 2$, in general $\theta_{p}\left(v, v^{\prime}\right) \neq \theta_{p}\left(v^{\prime}, v\right)$, but it is satisfied $\theta_{p}\left(v, v^{\prime}\right)=\theta_{p^{\circ}}\left(v^{\prime}, v\right)$.

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## Proposition 1

Assume $\mathbb{R}^{n}$ is endowed with an $\ell_{p}$-norm with $p \in(1,+\infty)$. Consider the map between normed spaces $\left(\mathbb{R}^{n},\|\cdot\|_{p}\right) \rightarrow\left(\mathbb{R}^{n},\|\cdot\|_{p^{\circ}}\right)$ that associates to $v=\left(v_{1}, \ldots, v_{d}\right)^{T}$ the vector $v^{\circ}=\left(\left(\frac{\left|v_{1}\right|}{\|v\|_{p}}\right)^{p-1} \operatorname{sign}\left(v_{1}\right)\|v\|_{p}, \ldots,\left(\frac{\left|v_{n}\right|}{\|v\|_{p}}\right)^{p-1} \operatorname{sign}\left(v_{n}\right)\|v\|_{p}\right)^{T}$ if $v$ is not the zero vector, otherwise $v^{\circ}$ is the zero vector. Then, given $v \in \mathbb{R}^{n}$, the vector $v^{\circ}$ is the unique vector in $\mathbb{R}^{n}$ satisfaying $\|v\|_{p}=\left\|v^{\circ}\right\|_{p^{\circ}}$ and $\theta_{p}\left(v, v^{\circ}\right)=0$.

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## Definition (Polar vector)

Assume $\mathbb{R}^{n}$ is endowed with an $\ell_{p}$-norm with $p \in(1,+\infty)$ and let $v \in \mathbb{R}^{n}$. The polar vector of $v$ is the vector $v^{\circ}$ given in Proposition 1.

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## Generalized Snell's law

## Generalized Snell's law - Dot product form



$$
\begin{aligned}
& w_{A}\left(\frac{(c-a)^{\circ}}{\left\|(c-a)^{\circ}\right\|_{p_{A}^{\circ}}}\right)^{T} v \\
& =w_{B}\left(\frac{(b-c)^{\circ}}{\left\|(b-c)^{\circ}\right\|_{p_{B}^{\circ}}}\right)^{T} v
\end{aligned}
$$

for all non-zero vector $v \in V(H)$.

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## Generalized Snell's law - Cosine form

$$
\begin{aligned}
& w_{A}\|v\|_{p_{A}} \cos \theta_{p_{A}^{\circ}}\left((c-a)^{\circ}, v\right) \\
& =w_{B}\|v\|_{p_{B}} \cos \theta_{p_{B}^{\circ}}\left((b-c)^{\circ}, v\right)
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for all non-zero vector $v \in V(\operatorname{aff}(H))$.

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$$
\begin{aligned}
& w_{A}\|v\|_{p_{A}} \cos \theta_{p_{A}^{\circ}}\left((c-a)^{\circ}, v\right) \\
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$$

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# Many thanks for your attention. 

