

Estimate for the Stokes system:

Optimality issues

December 1st, 2025

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$$\begin{cases} \partial_t U - \Delta U + \nabla q = F & \text{on } M \text{ smooth open set of } \mathbb{R}^d \\ \operatorname{div} U = h \end{cases}$$

+ initial conditions

+ Boundary conditions, general (Lopatinskiĭ - Sapiro type) precise conditions given below

typical examples: • Dirichlet $U|_\partial = G$

• Navier: $\nu \cdot U = G_\nu \quad \left((\nabla U + {}^t \nabla U) \cdot \nu \right)_{\tan} = G_{\tan}$

• Neumann $({}^t \nabla U + \kappa \nabla U) \nu - q \nu = G$

Observability

$T > 0$

$\omega \subset \mathcal{M}$ open subset

$$\int_0^T (\|v\|^2 + \|q\|^2) dt \lesssim \int_0^T (\|v\|_{L^2(\omega)}^2 + \|q\|_{L^2(\omega)}^2) dt \\ + \int_0^T (\|F\|^2 + \|h\|^2 + |G|^2) dt$$

$\uparrow$
boundary
value

Ref: homogeneous Dirichlet . Fernandez-Cara, Guerrero, Immanuilo, Puel 04
+ flat Laplace . Buefe, Takahashi 25

Application observability / null controllability of Oseen system

NS (local result)

• Navier: Guerrero 2006

Fernandez-Cara, Gonzalez-Burgos, Immanuilo, Puel (2006-2008)

One strategy $\partial_t U - \Delta U = F - \nabla q$ + homog. Dirichlet

heat-type Carleman estimate for U .

Apply divergence and use $\operatorname{div} U = 0$

$\Delta q = \operatorname{div} F$ No boundary condition.

Multiplier + microlocal argument $\rightarrow$ estimation of $q/24$

Elliptic Carleman estimate for q + time integration

$\rightarrow$ combine estimations.

Carleman estimates - elliptic case

Estimations of the form

$$\tau^{\frac{3}{2}} \|e^{\tau\varphi} u\|_{L^2} + \tau^{\frac{1}{2}} \|e^{\tau\varphi} \nabla u\|_{L^2} \leq C \|e^{\tau\varphi} A u\|$$

- A order 2, elliptic
- $\varphi = \varphi(x)$ weight function.
- $u \in C_c^\infty$, $\tau > 0$ large
- if u defined at a boundary

boundary condition
(order k)

$$\tau^{\frac{3}{2}} \|e^{\tau\varphi} u\|_{L^2} + \tau^{\frac{1}{2}} \|e^{\tau\varphi} \nabla u\|_{L^2} \leq C \left(\|e^{\tau\varphi} A u\|_{L^2} + |e^{\tau\varphi} B u|_{\frac{3-k}{2}} \right) + \text{Observation term}$$

+ $\tau^{\frac{3}{2}} |e^{\tau\varphi} u|_{\partial} |_{L^2} + \tau^{\frac{1}{2}} |e^{\tau\varphi} \nabla u|_{\partial} |_{L^2}$

optimal?

Carleman estimates - Parabolic version (Fursikov-Imanuvilov)

$$\left. \begin{aligned} & \| \tau^{\frac{3}{2}} e^{\tau \eta \phi} u \|_{L^2} + \| \tau^{\frac{1}{2}} e^{\tau \eta \phi} \nabla u \|_{L^2} \leq C \| e^{\tau \eta \phi} P u \|_{L^2} \end{aligned} \right\} \begin{array}{l} \text{Optimal} \\ ? \end{array}$$

$$\cdot P = \partial_t - \Delta \quad \cdot u \in C_c^\infty, \tau > 0 \text{ large}$$

$$\cdot \gamma = \gamma(x) \text{ weight function. } \eta = \frac{1}{t(T-t)}$$

$$\cdot \phi = \gamma - \kappa < 0$$

$$\cdot \tau^2 = \tau \eta \phi$$

Back to Stokes — Away from the boundary

$$\partial_t U - \Delta U + \nabla q = F$$

$$\operatorname{div}_g U = h$$

$$\gamma^{\frac{1}{2}} \left(\left\| \tilde{\sigma}^{\frac{1}{2}} e^{\tau \eta \phi} q \right\|_{L_x} + \left\| \tilde{\sigma}^{-\frac{1}{2}} e^{\tau \eta \phi} \nabla q \right\|_{L_x} \right)$$

← velocity

$$+ \gamma \left(\left\| \tilde{\sigma} e^{\tau \eta \phi} U \right\|_{L_x} + \left\| e^{\tau \eta \phi} \nabla U \right\|_{L_x} \right)$$

← pressure

$$\lesssim \left\| e^{\tau \eta \phi} F \right\|_{L_x} + \left\| e^{\tau \eta \phi} \partial_t h \right\|_{-1} + \gamma^{\frac{1}{2}} \left\| \tilde{\sigma}^{-\frac{1}{2}} e^{\tau \eta \phi} \Delta h \right\|_{-1}$$

• pressure q : $\frac{1}{2}$ derivative loss

• velocity U full derivative loss

} Optimal ?

At a boundary

Theorem (LR - Robbiano)

$$\gamma^{\frac{1}{2}} \left(\left\| \tilde{\sigma}^{\frac{1}{2}} e^{\tau\eta\phi} q \right\|_{L^2} + \left\| \tilde{\sigma}^{-\frac{1}{2}} e^{\tau\eta\phi} \nabla q \right\|_{L^2} \right) + \gamma \left(\left\| \tilde{\sigma} e^{\tau\eta\phi} u \right\|_{L^2} + \left\| e^{\tau\eta\phi} \nabla u \right\|_{L^2} \right)$$

$$+ \left| \tilde{\sigma}^{\frac{3}{2}} e^{\tau\eta\phi} u \right|_{\partial\Omega} + \left| \tilde{\sigma}^{\frac{1}{2}} e^{\tau\eta\phi} \nabla u \right|_{\partial\Omega} + \left| \tilde{\sigma}^{\frac{1}{2}} e^{\tau\eta\phi} q \right|_{\partial\Omega}$$

$$\lesssim \sum_j |B_j u|_{\partial\Omega} + \text{source terms}$$

Theorem (LR - Robbiano)

$$\gamma^{\frac{1}{2}} \left(\left\| \tilde{\sigma}^{\frac{1}{2}} e^{\tau\eta\phi} q \right\|_{L^2_x} + \left\| \tilde{\sigma}^{-\frac{1}{2}} e^{\tau\eta\phi} \nabla q \right\|_{L^2_x} \right) + \gamma \left(\left\| \tilde{\sigma} e^{\tau\eta\phi} U \right\|_{L^2_x} + \left\| e^{\tau\eta\phi} \nabla U \right\|_{L^2_x} \right) \\ + \left| \tilde{\sigma}^{\frac{3}{2}} e^{\tau\eta\phi} U \right|_{\partial\mathcal{M}_{t,x}} + \left| \tilde{\sigma}^{\frac{1}{2}} e^{\tau\eta\phi} \nabla U \right|_{\partial\mathcal{M}_{t,x}} + \left| \tilde{\sigma}^{\frac{1}{2}} e^{\tau\eta\phi} q \right|_{\partial\mathcal{M}_{t,x}}$$

$$\lesssim \sum_j \left| B_j u \right|_{\partial\mathcal{M}_{t,x}} + \text{source terms}$$

Optimal?

Optimality: estimation away from the boundary suffices

pressure estimation: $\operatorname{div} ((\partial_t - \Delta)U + \nabla q) = \operatorname{div} F$

$$\rightarrow (\partial_t - \Delta)h + \Delta q = F \rightarrow \Delta(q - h) = \operatorname{div} F - \partial_t h$$

Carleman estimate for $q - h$

$$\gamma^{\frac{1}{2}} \|\varrho^{-\frac{1}{2}}(q - h)\|_{\tilde{\Lambda}, 1} \lesssim \|F\|_{L^2} + \|\partial_t h\|_{\tilde{\Lambda}, -1}$$

$$\gamma^{\frac{1}{2}} \|\varrho^{-\frac{1}{2}} q\|_{\tilde{\Lambda}, 1} \lesssim \|F\|_{L^2} + \|\partial_t h\|_{\tilde{\Lambda}, -1} + \gamma^{\frac{1}{2}} \|\varrho^{-\frac{1}{2}} h\|_{\tilde{\Lambda}, 1}$$

Velocity estimation

$$V = \begin{pmatrix} U^\phi \\ \Theta^{-1} q^\phi \end{pmatrix} \in \mathbb{R}^{d+1}$$

$$\Theta = \Theta_p(\lambda)$$

Stokes reads $AV = G + \text{error terms}$

$$A = \begin{pmatrix} I^\phi & -i \nabla_g^\phi \Theta \\ -i \Theta \operatorname{div}^\phi & 0 \end{pmatrix}$$

$${}^t a = \begin{pmatrix} P^\phi I_d & \lambda \} \\ \lambda {}^t \zeta g & 0 \end{pmatrix}$$

$$\zeta = \zeta + i\tau d\phi = \zeta + i\bar{z} d\psi$$

Eigenvectors

$$\begin{pmatrix} \vartheta \\ 0 \end{pmatrix}$$

for $\vartheta \perp_g \zeta$

p^ϕ eigenvalue

$\rightarrow d-1$ vectors

${}^t \begin{pmatrix} \vartheta \\ 0 \end{pmatrix} V$ can be estimated with a loss of $\frac{1}{2}$ derivative

$$W_q = \begin{pmatrix} 0 \\ 1 \end{pmatrix}$$

$$W_1 = \begin{pmatrix} \lambda^{-1} \bar{\zeta} \\ 0 \end{pmatrix}$$

$\rightarrow$ not an eigenvector

$$\bar{\zeta} \not\perp_g \zeta$$

$${}^t W_1 a = {}^t W_1 P + {}^t \zeta g \bar{\zeta} W_q$$

$\downarrow$
pressure estimate obtained above

$${}^tW_{1,a} = {}^tW_{1,p} + {}^t\mathcal{G}\mathcal{G}^T W_q$$

${}^tW_1 V$ is estimated from ${}^tW_q V$ with additional loss of $\frac{1}{2}$ derivative

$\Rightarrow {}^tW_1 V$ is estimated with a loss of a full derivative

$\Rightarrow$ loss of a full derivative for the velocity.

Culprit? All evidences point to $W_1 = \begin{pmatrix} \mathcal{I}^T \mathcal{G} \\ 0 \end{pmatrix}$
 El culpable

Optimality

Theorem. Suppose $T > 0$ and there exist $C > 0$ and $\tau_0 > 0$ such that

$$\tau^\alpha \| \eta e^{\tau \eta \phi} U \|_{L^2} + \tau^\beta \| \eta^{\frac{1}{2}} e^{\tau \eta \phi} q \|_{L^2}$$

$$\leq C \left(\| e^{\tau \eta \phi} (\partial_t - \Delta) U + \nabla q \|_{L^2} + \| e^{\tau \eta \phi} \partial_t \operatorname{div} U \|_{\tilde{\lambda}, -1} + \| \tau^{-\frac{1}{2}} e^{\tau \eta \phi} \operatorname{div} U \|_{\tilde{\lambda}, 1} \right)$$

for $\tau \geq \tau_0$, $U \in \mathcal{C}_c^\infty((0, T) \times \Omega; \mathbb{C}^d)$ and $q \in \mathcal{C}_c^\infty((0, T) \times \Omega; \mathbb{C})$.

Then, $\alpha \leq 1$ and $\beta \leq \frac{1}{2}$

How to prove optimality? Elliptic case $P(D) = -\Delta = D^2$

- $x^0 \in \Omega$, $d\phi(x^0) \neq 0$, $\zeta^0 \in \mathbb{R}^d$ such that
$$\begin{cases} \tau \zeta^0 \cdot d\phi(x^0) = 0 \\ \text{and } |\zeta^0| = \tau |d\phi(x^0)| \end{cases}$$

Then, $a_\phi = (\xi_j + i\tau \partial_j \phi)^2 = 0$ at (x^0, τ^0, ζ^0)

- Set $w(x) = \zeta^0 \cdot x$ with $\zeta^0 = \zeta^0 + i\tau d\phi(x^0)$

$$\phi(x) - \operatorname{Im} w(x) = \phi(0) + G(x) + |x|^3 O(1) \quad G(x) = \frac{1}{2} \sum_{j,k} \partial_{jk}^2 \phi(0) x_j x_k$$

- $f \in \mathcal{C}_c^\infty(\mathbb{R}^d)$, $f \neq 0$ $u(x) = e^{i\tau(iw(x) - \phi(0))} f_\tau(x)$

$$f_\tau(x) = f(\tau^{1/2} x)$$

$$\bullet \int_{\mathbb{R}^d} e^{2\tau\phi} |u|^2 dx = \int_{\mathbb{R}^d} e^{2\tau(G(x) + |x|^3 \partial u)} |f_\tau(x)|^2 dx$$

$$= \tau^{-d/2} \int_{\mathbb{R}^d} e^{2(G(x) + \tau^{-1/2} |x|^3 \partial u)} |f(x)|^2 dx$$

$$\sim \tau^{-d/2} \|e^G f\|_{L^2(\mathbb{R}^d)}^2 \quad (\text{dominated convergence})$$

$$\bullet e^{\tau\phi} P u = e^{\tau(\phi - \phi(0) + i\omega)} \underbrace{e^{\tau(\phi(0) - i\omega)} P(D)}_{P(D + \tau \zeta^0)} e^{\tau(i\omega - \phi(0))} f_\tau$$

$$P(D + \tau \zeta^0) = \underbrace{P(\tau \zeta^0)}_{=0} + P'_\xi(\tau \zeta^0) \cdot D_x + \frac{1}{2} P''_\xi(\tau \zeta^0) (D_x, D_x)$$

$$P(D + \tau \zeta^0) f_\tau = \tau^{3/2} \left(P'_\xi(\zeta^0) (D_x f)_\tau + \tau^{-1/2} O(1) \right)$$

$$\|e^{\tau\phi} P(D)u\|_{L^2}^2 \sim K \tau^{3-d/2}$$

$$\tau^{2\alpha} \|e^{\tau\phi} u\|_{L^2}^2 \lesssim C \|e^{\tau\phi} P(D)u\|_{L^2}^2$$

$$\tau^{2\alpha - \frac{d}{2}} \lesssim \tau^{3-d/2}$$

$\Rightarrow$

$$\alpha \leq \frac{3}{2}$$

. Hörmander, 1985 (1963)

- LR, Lebeau, Robbiano 2023

Stokes now

same ζ^0 same $w(x)$

$$t \in [0, T] \leftrightarrow s \in \mathbb{R}$$
$$\frac{T}{2} \leftrightarrow s = 0$$

$$s = \tan\left(\frac{\pi t}{T} - \frac{\pi}{2}\right)$$

$$\partial_t = \frac{\pi \langle s \rangle^2}{T} \partial_s$$

$$P = \partial_t - \Delta = \frac{a}{T} \partial_s - \Delta$$

$$U = e^{\tau \eta (i\omega(x) - \phi(0))} f_\tau(s, x) U^0 \quad \text{with} \quad U^0 = \zeta^0 \#$$

$$q = \tau^{1/2} l_\tau(s, x) e^{\tau \eta (i\omega(x) - \phi(0))}$$

N.B. $tW_1 U$ does not vanish $\rightarrow$ contribution in the direction with the poor estimate

$$\bullet \tau^{2\alpha} \|\eta e^{\tau \eta \phi} U\|_{L^2}^2 \gtrsim \tau^{2\alpha - \frac{(d+1)}{2}} |U^0|^2 \|e^G f\|_{L^2}^2$$

$$\bullet \tau^{2\beta} \|\eta^{1/2} e^{\tau \eta \phi} q\|_{L^2}^2 \gtrsim \tau^{2\beta + 1 - \frac{(d+1)}{2}} \|e^G l\|_{L^2}^2$$

$$\bullet \left\| (\delta\eta)^{-\frac{1}{2}} e^{\tau\eta} \operatorname{div} U \right\|_{\tilde{\lambda}, 1}^2 + \left\| e^{\tau\eta} \langle s \rangle^2 \partial_s \operatorname{div} U \right\|_{L^2}^2 \lesssim \tau^{2 - \frac{(d+1)}{2}}$$

$$e^{\tau\eta} (\phi(0) - i\omega(x)) (a\partial_s - \Delta) U = -\tau^{3/2} \left(P'_\xi(\xi^0) (\mathcal{D}_x f)_\tau + \tau^{-1/2} \mathcal{O}(1) \right) U^0$$

$$e^{\tau\eta} (\phi(0) - i\omega(x)) \nabla q = \tau^{3/2} \left(i l_\tau U^0 + \tau^{-1/2} \mathcal{O}(1) \right)$$

$$\uparrow \\ U^0 = (\xi^0)^\#$$

$$\text{if } l = P'_\xi(\xi^0) \cdot \mathcal{D}_x f$$

$$\text{then } e^{\tau\eta} (\phi(0) - i\omega(x)) \left((a\partial_s - \Delta) U + \nabla q \right) = \tau \mathcal{O}(1)$$

$$\left\| e^{\tau\eta} \phi \left((a\partial_s - \Delta) U + \nabla q \right) \right\|_{L^2}^2 \lesssim \tau^{2 - \frac{(d+1)}{2}}.$$

$$\Rightarrow RMS \leq \tau^2 - \frac{(d+1)}{2}$$

$$\bullet \tau^{2\alpha} \|\eta e^{\tau\eta\phi} U\|_{L^2}^2 \geq \tau^{2\alpha - \frac{(d+1)}{2}} |U^0|^2 \|e^G f\|_{L^2}^2$$

$$\bullet \tau^{2\beta} \|\eta^{\frac{1}{2}} e^{\tau\eta\phi} q\|_{L^2}^2 \geq \tau^{2\beta + 1 - \frac{(d+1)}{2}} \|e^G l\|_{L^2}^2$$

$\Rightarrow$

$$\alpha \leq 1$$

it's optimal.

$$\beta \leq \frac{1}{2}$$

Thank you.

Carleman estimates

Elliptic estimate

ideas behind the proof.

$$\tau^{3/2} \|e^{\tau\varphi} u\|_{L^2} + \tau^{1/2} \|e^{\tau\varphi} \nabla u\|_{L^2} \leq C \|e^{\tau\varphi} Pu\|_{L^2}$$

$$P_\varphi = e^{\tau\varphi} P e^{-\tau\varphi}$$

$$\|P_\varphi v\| \gtrsim \tau^{3/2} \|v\| + \tau^{1/2} \|\nabla v\|$$

Lemma if $|\Delta\varphi| \geq c > 0$ and $\varphi = e^{\delta\chi}$ then subelliptic property

Dependence on δ (Carleman second large parameter)

$$\frac{\delta}{\tau} (q_2^2 + q_1^2) + \{q_2, q_1\} \gtrsim \frac{\delta}{\tau} (\tau^4 + |\xi|^4) \left. \vphantom{\frac{\delta}{\tau}} \right\} \text{optimal?}$$

$$\|P_\varphi v\| \gtrsim \tau^{1/2} \left(\|\tau^{3/2} v\| + \|\tau^{1/2} \nabla v\| + \|\tau^{-1/2} D^2 v\| \right)$$