

Splitting methods for constructing the resolvent of a sum of maximal monotone operators

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Sevilla, April 12, 2010

Overview: Solving strongly monotone inclusions

Throughout, \mathcal{H} is a real Hilbert space.

- Given $r \in \mathcal{H}$ and maximal monotone operators $(B_i)_{1 \leq i \leq m}$ acting on \mathcal{H} , with B_1 strongly monotone,

$$\text{Find } x \in \mathcal{H} \text{ such that } r \in \sum_{i=1}^m B_i x.$$

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- Equivalent formulation:** Given $r \in \mathcal{H}$ and maximal monotone operators $(A_i)_{1 \leq i \leq m}$ on \mathcal{H} , weights $(\omega_i)_{1 \leq i \leq m}$ in $]0, 1[$ such that $\sum_{i=1}^m \omega_i = 1$, solve $r \in \sum_{i=1}^m \omega_i A_i x$, i.e., compute

$$x = (\text{Id} + A)^{-1} r = J_A r, \quad \text{where } A = \sum_{i=1}^m \omega_i A_i.$$

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- We propose two algorithms to construct $J_A r$.

PART I: Douglas-Rachford splitting

A first algorithm to construct J_{Ar} .

Douglas-Rachford splitting for two monotone operators

Douglas-Rachford (1956), Lieutaud (1969), Lions-Mercier (1979), Eckstein-Bertsekas (1992),...

Algorithm 1

$(\mathcal{H}, \|\cdot\|)$ a real Hilbert space, \mathbf{A} and \mathbf{B} maximal monotone operators from \mathcal{H} to $2^{\mathcal{H}}$ such that $\text{zer}(\mathbf{A} + \mathbf{B}) \neq \emptyset$, $\gamma \in]0, +\infty[$, $(\lambda_n)_{n \in \mathbb{N}}$ in $]0, 2]$, and $(\mathbf{a}_n)_{n \in \mathbb{N}}$ and $(\mathbf{b}_n)_{n \in \mathbb{N}}$ in \mathcal{H} .

Routine:

Initialization

$$\left[\mathbf{z}_0 \in \mathcal{H} \right.$$

For $n = 0, 1, \dots$

$$\left[\begin{array}{l} \mathbf{y}_n = J_{\gamma \mathbf{B}} \mathbf{z}_n + \mathbf{b}_n \\ \mathbf{z}_{n+1} = \mathbf{z}_n + \lambda_n (J_{\gamma \mathbf{A}} (2\mathbf{y}_n - \mathbf{z}_n) + \mathbf{a}_n - \mathbf{y}_n). \end{array} \right.$$

Douglas-Rachford splitting for two monotone operators

Theorem

- Suppose that $\sum_{n \in \mathbb{N}} \lambda_n (\|\mathbf{a}_n\| + \|\mathbf{b}_n\|) < +\infty$,
 $\sum_{n \in \mathbb{N}} \lambda_n (2 - \lambda_n) = +\infty$, and $(\forall n \in \mathbb{N}) \lambda_n < 2$. Then:
 - $(\mathbf{z}_n)_{n \in \mathbb{N}}$ converges weakly to a point $\mathbf{z} \in \mathcal{H}$ and $J_{\gamma \mathbf{B}} \mathbf{z}$ is a zero of $\mathbf{A} + \mathbf{B}$ [PLC, 2004].

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 - Suppose that $\mathbf{A} = N_{\mathbf{D}}$, where \mathbf{D} is a closed affine subspace of \mathcal{H} . Then $J_{\gamma \mathbf{A}} \mathbf{z}_n \rightarrow \mathbf{y} \in \text{zer}(\mathbf{A} + \mathbf{B})$.
 - Suppose that $\mathbf{A} = N_{\mathbf{D}}$, where \mathbf{D} is a closed vector subspace of \mathcal{H} , and that $\mathbf{b}_n \rightarrow 0$. Then $J_{\gamma \mathbf{A}} \mathbf{y}_n \rightarrow \mathbf{y} \in \text{zer}(\mathbf{A} + \mathbf{B})$.
- Suppose that $\sum_{n \in \mathbb{N}} \| \mathbf{a}_n \| < +\infty$, $\sum_{n \in \mathbb{N}} \| \mathbf{b}_n \| < +\infty$, $\inf_{n \in \mathbb{N}} \lambda_n > 0$, and \mathbf{B} is uniformly monotone on the bounded subsets of \mathcal{H} . Then $\mathbf{y}_n \rightarrow \mathbf{y} \in \text{zer}(\mathbf{A} + \mathbf{B})$.

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- Suppose that $\sum_{n \in \mathbb{N}} \|\mathbf{a}_n\| < +\infty$, $\sum_{n \in \mathbb{N}} \|\mathbf{b}_n\| < +\infty$, $\inf_{n \in \mathbb{N}} \lambda_n > 0$, and \mathbf{B} is uniformly monotone on the bounded subsets of \mathcal{H} . Then $\mathbf{y}_n \rightarrow \mathbf{y} \in \text{zer}(\mathbf{A} + \mathbf{B})$. *In particular this covers Peaceman-Rachford splitting.*

Douglas-Rachford splitting for two monotone operators

Setting $A = N_D$, where D is a closed affine subspace of \mathcal{H} , we obtain:

Algorithm 2

$$\mathbf{z}_0 \in \mathcal{H} \quad \text{and} \quad (\forall n \in \mathbb{N}) \quad \left\{ \begin{array}{l} \mathbf{y}_n = J_{\gamma \mathbf{B}} \mathbf{z}_n + \mathbf{b}_n \\ \mathbf{x}_n = P_D \mathbf{y}_n \\ \mathbf{p}_n = P_D \mathbf{z}_n \\ \mathbf{z}_{n+1} = \mathbf{z}_n + \lambda_n (2\mathbf{x}_n - \mathbf{p}_n - \mathbf{y}_n). \end{array} \right.$$

Corollary

- Suppose that $\sum_{n \in \mathbb{N}} \lambda_n \|\mathbf{b}_n\| < +\infty$, $\sum_{n \in \mathbb{N}} \lambda_n (2 - \lambda_n) = +\infty$, and $(\forall n \in \mathbb{N}) \lambda_n < 2$. Then $\mathbf{p}_n \rightarrow \mathbf{p} \in \text{zer}(N_D + \mathbf{B})$.
- Suppose that $\sum_{n \in \mathbb{N}} \|\mathbf{b}_n\| < +\infty$, $\inf_{n \in \mathbb{N}} \lambda_n > 0$, and \mathbf{B} is uniformly monotone on the bounded subsets of \mathcal{H} . Then $\mathbf{x}_n \rightarrow \mathbf{x} \in \text{zer}(N_D + \mathbf{B})$.

Splitting for m monotone operators

- $(B_i)_{1 \leq i \leq m}$ are maximal monotone operators from \mathcal{H} to $2^{\mathcal{H}}$, and

$$B = \sum_{i=1}^m \omega_i B_i, \quad \text{where } \{\omega_i\}_{1 \leq i \leq m} \subset]0, 1[\quad \text{and} \quad \sum_{i=1}^m \omega_i = 1.$$

- \mathcal{H} is the m -fold Cartesian product of \mathcal{H} with scalar product $(\mathbf{x}, \mathbf{y}) \mapsto \sum_{i=1}^m \omega_i \langle x_i | y_i \rangle$.
- $\mathbf{A} = N_{\mathbf{D}}$, where $\mathbf{D} = \{(x, \dots, x) \in \mathcal{H} \mid x \in \mathcal{H}\}$.
- $\mathbf{B}: \mathcal{H} \rightarrow 2^{\mathcal{H}}: \mathbf{x} \mapsto \bigtimes_{i=1}^m B_i x_i$.
- $\mathbf{j}: \mathcal{H} \rightarrow \mathbf{D}: x \mapsto (x, \dots, x)$.
- Thus, $\mathbf{j}(\text{zer } B) = \text{zer } (N_{\mathbf{D}} + \mathbf{B})$.

Splitting for m monotone operators

Algorithm 3

Initialization

For $i = 1, \dots, m$
 $\left[\begin{array}{l} z_{i,0} \in \mathcal{H} \end{array} \right.$

For $n = 0, 1, \dots$

For $i = 1, \dots, m$
 $\left[\begin{array}{l} y_{i,n} = J_{\gamma B_i} z_{i,n} + b_{i,n} \\ x_n = \sum_{i=1}^m \omega_i y_{i,n} \\ p_n = \sum_{i=1}^m \omega_i z_{i,n} \\ \lambda_n \in]0, 2] \end{array} \right.$
 For $i = 1, \dots, m$
 $\left[\begin{array}{l} z_{i,n+1} = z_{i,n} + \lambda_n (2x_n - p_n - y_{i,n}). \end{array} \right.$

Splitting for m monotone operators

Proposition

- Suppose that $\max_{1 \leq i \leq m} \sum_{n \in \mathbb{N}} \lambda_n \|b_{i,n}\| < +\infty$, $\sum_{n \in \mathbb{N}} \lambda_n (2 - \lambda_n) = +\infty$, and $(\forall n \in \mathbb{N}) \lambda_n < 2$. Then:
 - $p_n \rightarrow p \in \text{zer } B$.
 - Suppose that $(\forall i \in \{1, \dots, m\}) b_{i,n} \rightarrow 0$. Then $x_n \rightarrow x \in \text{zer } B$.
- Suppose that $\max_{1 \leq i \leq m} \sum_{n \in \mathbb{N}} \|b_{i,n}\| < +\infty$, $\inf_{n \in \mathbb{N}} \lambda_n > 0$, and the B_i s are strongly monotone. Then $x_n \rightarrow x \in \text{zer } B$. ▲▲

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Remark

A special case of ▲▲ was obtained by Spingarn (1983) via the method of partial inverses.

Splitting for m monotone operators

Spingarn's splitting algorithm

Initialization

$$\left[\begin{array}{l} s_0 \in \mathcal{H} \\ (v_{i,0})_{1 \leq i \leq m} \in \mathcal{H}^m \text{ satisfy } \sum_{i=1}^m \omega_i v_{i,0} = 0 \end{array} \right.$$

For $n = 0, 1, \dots$

$$\left[\begin{array}{l} \text{For } i = 1, \dots, m \\ \quad \left[\text{find } (y_{i,n}, u_{i,n}) \in \text{gr } B_i \text{ such that } y_{i,n} + u_{i,n} = s_n + v_{i,n} \right. \\ \\ s_{n+1} = \sum_{i=1}^m \omega_i y_{i,n} \\ q_n = \sum_{i=1}^m \omega_i u_{i,n} \\ \text{For } i = 1, \dots, m \\ \quad \left[v_{i,n+1} = u_{i,n} - q_n. \right. \end{array} \right.$$

Splitting for the resolvent of the sum

Back to our problem...

- $(A_i)_{1 \leq i \leq m}$ are maximal monotone
- Set

$$A = \sum_{i=1}^m \omega_i A_i, \quad \text{where } \{\omega_i\}_{1 \leq i \leq m} \subset]0, 1[\quad \text{and} \quad \sum_{i=1}^m \omega_i = 1.$$

- Let $r \in \text{ran}(\text{Id} + A)$
- The goal is to construct $J_A r$.

Splitting for the resolvent of the sum

Algorithm 4

Let $\gamma \in]0, +\infty[$, $(\lambda_n)_{n \in \mathbb{N}}$ in $]0, 2]$, and, for every $i \in \{1, \dots, m\}$, $(a_{i,n})_{n \in \mathbb{N}}$ in \mathcal{H} .

Initialization

For $i = 1, \dots, m$
 $\quad z_{i,0} \in \mathcal{H}$

For $n = 0, 1, \dots$

For $i = 1, \dots, m$
 $\quad y_{i,n} = J_{\frac{\gamma}{\gamma+1} A_i} \left((z_{i,n} + \gamma r) / (\gamma + 1) \right) + a_{i,n}$
 $\quad x_n = \sum_{i=1}^m \omega_i y_{i,n}$
 $\quad p_n = \sum_{i=1}^m \omega_i z_{i,n}$
 For $i = 1, \dots, m$
 $\quad z_{i,n+1} = z_{i,n} + \lambda_n (2x_n - p_n - y_{i,n}).$

Splitting for the resolvent of the sum

Proposition

Suppose that $\inf_{n \in \mathbb{N}} \lambda_n > 0$ and that $\max_{1 \leq i \leq m} \sum_{n \in \mathbb{N}} \|a_{i,n}\| < +\infty$.
Then $x_n \rightarrow J_A r$.

Proof: Set

$$(\forall i \in \{1, \dots, m\}) \quad B_i: \mathcal{H} \rightarrow 2^{\mathcal{H}}: y \mapsto -r + y + A_i y$$

in $\blacktriangle\blacktriangle$.

The proximity operator of the sum

- Let $(f_i)_{1 \leq i \leq m}$ be functions in $\Gamma_0(\mathcal{H})$ such that $\bigcap_{i=1}^m \text{dom } f_i \neq \emptyset$.

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- For every $r \in \mathcal{H}$,

$$\text{prox}_f r = \operatorname{argmin}_{x \in \mathcal{H}} f(x) + \frac{1}{2} \|r - x\|^2$$

is uniquely defined.

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- Setting $A_i = \partial f_i$ in Algorithm 4 **and** assuming some CQ so that $\partial f = \sum_{i=1}^m \omega_i A_i$, we can construct $\text{prox}_f r$.

Some applications of splitting in signal processing

- PLC and V. R. Wajs, “Signal recovery by proximal forward-backward splitting,” *Multiscale Model. Simul.*, vol. 4, pp. 1168-1200, 2005.
- C. Chaux, PLC, J.-C. Pesquet, and V. R. Wajs, “A variational formulation for frame-based inverse problems,” *Inverse Problems*, vol. 23, pp. 1495-1518, 2007.
- PLC and J.-C. Pesquet, “Proximal thresholding algorithm for minimization over orthonormal bases,” *SIAM J. Optim.*, vol. 18, pp. 1351–1376, 2007.
- PLC and J.-C. Pesquet, “A Douglas-Rachford splitting approach to nonsmooth convex variational signal recovery,” *IEEE J. Selected Topics Signal Process.*, vol. 1, pp 564–574, 2007.
- PLC and J.-C. Pesquet, “A proximal decomposition method for solving convex variational inverse problems,” vol. 24, 2008.

PART II: A Dykstra-like approach

A second algorithm to construct J_{Ar} .

Von Neumann's alternating projections algorithm

Theorem (von Neumann, 1933)

Let $r \in \mathcal{H}$, let U and V be closed vector subspaces of \mathcal{H} , and set

$$y_0 = r \quad \text{and} \quad (\forall n \in \mathbb{N}) \quad \begin{cases} x_n = P_V y_n \\ y_{n+1} = P_U x_n. \end{cases}$$

Then $x_n \rightarrow P_{U \cap V} r$.

- Von Neumann's theorem is a **best approximation** result.
- If U and V are intersecting closed convex subsets of \mathcal{H} , we merely have $x_n \rightarrow x$, where $x \in U \cap V$ is undetermined (Bregman, 1965).

Dykstra's alternating projections algorithm

Theorem (Boyle/Dykstra, 1986)

Let $z \in \mathcal{H}$, let C and D be closed **convex subsets** of \mathcal{H} such that $C \cap D \neq \emptyset$, and set

$$\left[\begin{array}{l} y_0 = r \\ \text{and } (\forall n \in \mathbb{N}) \end{array} \right. \left[\begin{array}{l} x_n = P_D(y_n) \\ y_{n+1} = P_C(x_n) \end{array} \right]$$

Then $x_n \rightarrow x \in C \cap D$ [Bregman (1965)]

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$$\left[\begin{array}{l} y_0 = r \\ p_0 = 0 \\ q_0 = 0 \end{array} \right] \quad \text{and} \quad (\forall n \in \mathbb{N}) \quad \left[\begin{array}{l} x_n = P_D(y_n + q_n) \\ q_{n+1} = y_n + q_n - x_n \\ y_{n+1} = P_C(x_n + p_n) \\ p_{n+1} = x_n + p_n - y_{n+1}. \end{array} \right.$$

Then $x_n \rightarrow P_{C \cap D} r$.

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Then $x_n \rightarrow P_{C \cap D} r$.

- Von Neumann's theorem is a special case.
- Nontrivial incremental proofs: Dykstra 1983, Han 1988, Boyle/Dykstra 1986, Gaffke/Mathar 1989, De Pierro/lusem 1991, Bauschke/Borwein 1994, etc.

The resolvent of the sum of two monotone operators

Theorem (Bauschke/PLC, 2008)

Let $(\mathcal{H}, \|\cdot\|)$ be a real Hilbert space, and let \mathbf{A} and \mathbf{B} be maximal monotone operators from \mathcal{H} to $2^{\mathcal{H}}$.

Furthermore, let $\mathbf{r} \in \text{ran}(\mathbf{Id} + \mathbf{A} + \mathbf{B})$ and let $(\mathbf{x}_n)_{n \in \mathbb{N}}$ be the sequence generated by the following routine.

$$\begin{cases} \mathbf{y}_0 = \mathbf{r} \\ \mathbf{p}_0 = \mathbf{0} \\ \mathbf{q}_0 = \mathbf{0} \end{cases} \quad \text{and} \quad \begin{cases} \mathbf{x}_n = J_{\mathbf{B}}(\mathbf{y}_n + \mathbf{q}_n) \\ \mathbf{q}_{n+1} = \mathbf{y}_n + \mathbf{q}_n - \mathbf{x}_n \\ \mathbf{y}_{n+1} = J_{\mathbf{A}}(\mathbf{x}_n + \mathbf{p}_n) \\ \mathbf{p}_{n+1} = \mathbf{x}_n + \mathbf{p}_n - \mathbf{y}_{n+1}. \end{cases}$$

Then $\mathbf{x}_n \rightarrow J_{\mathbf{A}+\mathbf{B}} \mathbf{r}$.

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Theorem (Bauschke/PLC, 2008)

Let $(\mathcal{H}, \|\cdot\|)$ be a real Hilbert space, and let \mathbf{A} and \mathbf{B} be maximal monotone operators from \mathcal{H} to $2^{\mathcal{H}}$. Let $(\mathbf{a}_n)_{n \in \mathbb{N}}$ and $(\mathbf{b}_n)_{n \in \mathbb{N}}$ be sequences in \mathcal{H} such that

$$\sum_{n \in \mathbb{N}} \|\mathbf{a}_n\| < +\infty \quad \text{and} \quad \sum_{n \in \mathbb{N}} \|\mathbf{b}_n\| < +\infty.$$

Furthermore, let $\mathbf{r} \in \text{ran}(\text{Id} + \mathbf{A} + \mathbf{B})$ and let $(\mathbf{x}_n)_{n \in \mathbb{N}}$ be the sequence generated by the following routine.

$$\begin{cases} \mathbf{y}_0 = \mathbf{r} \\ \mathbf{p}_0 = \mathbf{0} \\ \mathbf{q}_0 = \mathbf{0} \end{cases} \quad \text{and} \quad \begin{cases} \mathbf{x}_n = J_{\mathbf{B}}(\mathbf{y}_n + \mathbf{q}_n) + \mathbf{b}_n \\ \mathbf{q}_{n+1} = \mathbf{y}_n + \mathbf{q}_n - \mathbf{x}_n \\ \mathbf{y}_{n+1} = J_{\mathbf{A}}(\mathbf{x}_n + \mathbf{p}_n) + \mathbf{a}_n \\ \mathbf{p}_{n+1} = \mathbf{x}_n + \mathbf{p}_n - \mathbf{y}_{n+1}. \end{cases}$$

Then $\mathbf{x}_n \rightarrow J_{\mathbf{A} + \mathbf{B}} \mathbf{r}$.

Proof outline

- Note that $\mathbf{q}_{n+1} + \mathbf{p}_n + \mathbf{x}_n = \mathbf{y}_n + \mathbf{q}_n + \mathbf{p}_n$ and $\mathbf{q}_n + \mathbf{p}_n = \mathbf{r} - \mathbf{y}_n$.
- Hence $\mathbf{r} = \mathbf{y}_n + \mathbf{q}_n + \mathbf{p}_n = \mathbf{q}_{n+1} + \mathbf{p}_n + \mathbf{x}_n$.
- Rewrite algorithm as

$$\left[\begin{array}{l} \mathbf{y}_0 = \mathbf{r} \\ \mathbf{q}_0 = \mathbf{0} \\ \mathbf{p}_0 = \mathbf{0} \end{array} \right. \quad \text{and} \quad (\forall n \in \mathbb{N}) \quad \left[\begin{array}{l} \mathbf{x}_n = J_B(\mathbf{r} - \mathbf{p}_n) + \mathbf{b}_n \\ \mathbf{q}_{n+1} = \mathbf{r} - \mathbf{p}_n - \mathbf{x}_n \\ \mathbf{y}_{n+1} = J_A(\mathbf{r} - \mathbf{q}_{n+1}) + \mathbf{a}_n \\ \mathbf{p}_{n+1} = \mathbf{r} - \mathbf{q}_{n+1} - \mathbf{y}_{n+1}. \end{array} \right.$$

- Set $\mathbf{u}_0 = -\mathbf{r}$ and $(\forall n \in \mathbb{N}) \mathbf{u}_n = \mathbf{p}_n - \mathbf{r}$ and $\mathbf{v}_n = -\mathbf{q}_{n+1}$.
- Then $\mathbf{v}_n - \mathbf{u}_n = \mathbf{x}_n$, $\mathbf{v}_n - \mathbf{u}_{n+1} = \mathbf{y}_{n+1}$, and

$$\begin{cases} \mathbf{v}_n = \mathbf{p}_n - \mathbf{r} + \mathbf{x}_n = \mathbf{u}_n + J_B(-\mathbf{u}_n) + \mathbf{b}_n \\ \mathbf{u}_{n+1} = \mathbf{p}_{n+1} - \mathbf{r} = -\mathbf{q}_{n+1} - \mathbf{y}_{n+1} = \mathbf{v}_n - J_A(\mathbf{v}_n + \mathbf{r}) - \mathbf{a}_n. \end{cases}$$

- Set $\mathbf{C}: \mathbf{v} \mapsto \mathbf{A}^{-1}(\mathbf{v} + \mathbf{r})$ and $\mathbf{D} = \mathbf{B}^{\sim} = -\mathbf{B}^{-1}(-\cdot)$.
- Then $\mathbf{C}^{-1} = -\mathbf{r} + \mathbf{A}$, $\mathbf{D}^{\sim} = \mathbf{B}$, $J_{\mathbf{C}} = \text{Id} - J_{\mathbf{A}}(\cdot + \mathbf{r})$, and $J_{\mathbf{D}} = \text{Id} + J_{\mathbf{B}} \circ (-\text{Id})$.
- Thus, $\mathbf{u}_0 = -\mathbf{r}$ and $(\forall n \in \mathbb{N}) \quad \begin{cases} \mathbf{v}_n &= J_{\mathbf{D}}\mathbf{u}_n + \mathbf{b}_n \\ \mathbf{u}_{n+1} &= J_{\mathbf{C}}\mathbf{v}_n - \mathbf{a}_n. \end{cases}$
- Using [Bauschke/PLC/Reich, 2005], get

$$\mathbf{r} \in \text{ran}(\text{Id} + \mathbf{A} + \mathbf{B}) \Leftrightarrow \text{Fix}(J_{\mathbf{C}}J_{\mathbf{D}}) \neq \emptyset.$$

- Deduce from Martinet's Lemma that there exists $\mathbf{u} \in \text{Fix}(J_{\mathbf{C}}J_{\mathbf{D}})$ such that

$$\mathbf{x}_n = \mathbf{v}_n - \mathbf{u}_n = \mathbf{b}_n + J_{\mathbf{D}}\mathbf{u}_n - \mathbf{u}_n \rightarrow J_{\mathbf{D}}\mathbf{u} - \mathbf{u}.$$

- Using [Bauschke/PLC/Reich, 2005], get

$$J_{\mathbf{D}}\mathbf{u} - \mathbf{u} = J_{\mathbf{C}^{-1} + \mathbf{D}^{\sim}} \mathbf{0} = J_{\mathbf{A} + \mathbf{B}} \mathbf{r}.$$

- Underlying duality: $0 \in \mathbf{C}\mathbf{x} + {}^1\mathbf{D}\mathbf{x} \Leftrightarrow 0 \in \mathbf{C}^{-1}\mathbf{u} + ({}^1\mathbf{D})^{\sim}\mathbf{u}.$

Lemma (Martinet, 1972)

Let T_1 and T_2 be firmly nonexpansive operators from \mathcal{H} to \mathcal{H} such that $\text{Fix}(T_1 T_2) \neq \emptyset$, and let $(\mathbf{e}_{1,n})$ and $(\mathbf{e}_{2,n})$ be sequences in \mathcal{H} such that $\sum_{n \in \mathbb{N}} \|\mathbf{e}_{1,n}\| < +\infty$ and $\sum_{n \in \mathbb{N}} \|\mathbf{e}_{2,n}\| < +\infty$. Let $(\mathbf{u}_n)_{n \in \mathbb{N}}$ be the sequence resulting from the iteration

$$\mathbf{u}_0 \in \mathcal{H} \quad \text{and} \quad (\forall n \in \mathbb{N}) \quad \mathbf{u}_{n+1} = T_1(T_2 \mathbf{u}_n + \mathbf{e}_{2,n}) + \mathbf{e}_{1,n}.$$

Then there exists $\mathbf{u} \in \text{Fix}(T_1 T_2)$ such that $\mathbf{u}_n \rightarrow \mathbf{u}$. Moreover, $T_2 \mathbf{u}_n - \mathbf{u}_n \rightarrow T_2 \mathbf{u} - \mathbf{u}$.

Remarks

- In the case of normal cones, say $\mathbf{A} = N_C$ and $\mathbf{B} = N_D$, then $J_{\mathbf{A}} = P_C$ and $J_{\mathbf{B}} = P_D$.

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Remarks

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- The new algorithm therefore extends the original Dykstra algorithm.
- ... but the theorem does **not** capture the Boyle/Dykstra theorem since $J_{N_C+N_D} \neq P_{C \cap D}$!
- In addition, how to handle $m > 2$ maximal monotone operators ?

The resolvent of the sum of m monotone operators

Theorem

Let $(A_i)_{1 \leq i \leq m}$ be maximal monotone from \mathcal{H} to $2^{\mathcal{H}}$. Set

$$A = \sum_{i=1}^m \omega_i A_i, \text{ where } \{\omega_i\}_{1 \leq i \leq m} \subset]0, 1[\text{ and } \sum_{i=1}^m \omega_i = 1.$$

For every $i \in \{1, \dots, m\}$, let $(a_{i,n})_{n \in \mathbb{N}}$ be a sequence in \mathcal{H} such that $\sum_{n \in \mathbb{N}} \|a_{i,n}\| < +\infty$. Furthermore, let $r \in \text{ran}(Id + A)$ and set

$$\left[\begin{array}{l} x_0 = r \\ \text{For } i = 1, \dots, m \\ \quad \left[\begin{array}{l} z_{i,0} = x_0 \\ \text{For } i = 1, \dots, m \end{array} \right] \end{array} \right. \quad \text{and } (\forall n \in \mathbb{N}) \quad \left[\begin{array}{l} \text{For } i = 1, \dots, m \\ \quad \left[\begin{array}{l} y_{i,n} = J_{A_i} z_{i,n} + a_{i,n} \\ x_{n+1} = \sum_{i=1}^m \omega_i y_{i,n} \\ \text{For } i = 1, \dots, m \\ \quad \left[\begin{array}{l} z_{i,n+1} = x_{n+1} + z_{i,n} - y_{i,n} \end{array} \right] \end{array} \right. \end{array} \right.$$

Then $x_n \rightarrow J_A r$.

Proof outline

- $\mathcal{H} = \mathcal{H}^m$ with $(\mathbf{x}, \mathbf{y}) \mapsto \sum_{i=1}^m \omega_i \langle x_i \mid y_i \rangle$.
- $\mathbf{A}: \mathbf{x} \mapsto \prod_{i=1}^m A_i x_i$.
- $\mathbf{B} = N_{\mathbf{D}}$, where $\mathbf{D} = \{(x, \dots, x) \in \mathcal{H} \mid x \in \mathcal{H}\}$.
- $\mathbf{j}: \mathbf{x} \mapsto (x, \dots, x)$.
- $J_{\mathbf{A}}: \mathbf{x} \mapsto (J_{A_i} x_i)_{1 \leq i \leq m}$ and $J_{\mathbf{B}} = P_{\mathbf{D}}: \mathbf{x} \mapsto \mathbf{j} \left(\sum_{i=1}^m \omega_i x_i \right)$.
- $\mathbf{j}(J_{\mathbf{A}} r) = J_{\mathbf{A} + \mathbf{B}} \mathbf{j}(r)$.
- To construct $J_{\mathbf{A} + \mathbf{B}} \mathbf{j}(r)$ use Theorem 8 with $\mathbf{b}_n \equiv 0$.
- Since $J_{\mathbf{B}} = P_{\mathbf{D}}$, algorithm reduces to

$$\left[\begin{array}{l} \mathbf{y}_0 = \mathbf{j}(r) \\ \mathbf{p}_0 = 0 \end{array} \right] \quad \text{and} \quad (\forall n \in \mathbb{N}) \quad \left[\begin{array}{l} \mathbf{x}_n = P_{\mathbf{D}} \mathbf{y}_n \\ \mathbf{y}_{n+1} = J_{\mathbf{A}}(\mathbf{x}_n + \mathbf{p}_n) + \mathbf{a}_n \\ \mathbf{p}_{n+1} = \mathbf{x}_n + \mathbf{p}_n - \mathbf{y}_{n+1} \end{array} \right]$$

- After reordering and introducing $\mathbf{z}_n = \mathbf{x}_n + \mathbf{p}_n$:

$$\left[\begin{array}{l} \mathbf{x}_0 = P_D \mathbf{j}(r) \\ \mathbf{z}_0 = \mathbf{x}_0 \end{array} \right] \quad \text{and} \quad (\forall n \in \mathbb{N}) \quad \left[\begin{array}{l} \mathbf{y}_n = J_A \mathbf{z}_n + \mathbf{a}_n \\ \mathbf{x}_{n+1} = P_D \mathbf{y}_n \\ \mathbf{z}_{n+1} = \mathbf{x}_{n+1} + \mathbf{z}_n - \mathbf{y}_n. \end{array} \right.$$

- Now set $\mathbf{a}_n = (a_{i,n})_{1 \leq i \leq m}$, $\mathbf{y}_n = (y_{i,n})_{1 \leq i \leq m}$, and $\mathbf{z}_n = (z_{i,n})_{1 \leq i \leq m}$ to get $(\forall n \in \mathbb{N}) \mathbf{x}_n = \mathbf{j}(\mathbf{x}_n)$.
- Conclude that

$$\mathbf{x}_n = \mathbf{j}^{-1}(\mathbf{x}_n) \rightarrow \mathbf{j}^{-1}(J_{A+B} \mathbf{j}(r)) = J_A r.$$

The proximity operator of the sum

- Let $(f_i)_{1 \leq i \leq m}$ be functions in $\Gamma_0(\mathcal{H})$ such that $\bigcap_{i=1}^m \text{dom} f_i \neq \emptyset$.
- Set $f = \sum_{i=1}^m \omega_i f_i$, where $\{\omega_i\}_{1 \leq i \leq m} \subset]0, 1[$ and $\sum_{i=1}^m \omega_i = 1$.
- For every $r \in \mathcal{H}$,

$$\text{prox}_f r = \underset{x \in \mathcal{H}}{\text{argmin}} f(x) + \frac{1}{2} \|r - x\|^2$$

is uniquely defined.

- Setting $A_i = \partial f_i$ in the theorem **and** assuming some CQ so that $\partial f = \sum_{i=1}^m \omega_i A_i$, we can construct $\text{prox}_f r$.

The prox of the sum of two convex functions

Proposition [Bauschke/PLC/Reich, 2005]

Let $(\mathcal{H}, \|\cdot\|)$ be a real Hilbert space, and let φ and ψ be functions in $\Gamma_0(\mathcal{H})$ such that

$$\inf \varphi + \text{env}(\psi) > -\infty.$$

Set

$$\mathbf{u}_0 \in \mathcal{H} \text{ and } (\forall n \in \mathbb{N}) \mathbf{v}_n = \text{prox}_{\psi} \mathbf{u}_n \text{ and } \mathbf{u}_{n+1} = \text{prox}_{\varphi} \mathbf{v}_n.$$

Then $\mathbf{u}_n \rightarrow \mathbf{u}$, where $\mathbf{u} \in \text{argmin } \varphi + \text{env}(\psi)$, and $\text{prox}_{\psi} \mathbf{u}_n - \mathbf{u}_n \rightarrow \mathbf{w}$, where $\mathbf{w} = \text{prox}_{\varphi^* + \psi^{*\vee}} \mathbf{0}$ is the unique solution to the dual problem

$$\inf \varphi^* + \psi^{*\vee} + \frac{1}{2} \|\cdot\|^2.$$

The prox of the sum of two convex functions

Theorem (Bauschke/PLC, 2008)

Let $(\mathcal{H}, \|\cdot\|)$ be a real Hilbert space, and let \mathbf{f} and \mathbf{g} be functions in $\Gamma_0(\mathcal{H})$ such that $\text{dom}\mathbf{f} \cap \text{dom}\mathbf{g} \neq \emptyset$. Furthermore, let $\mathbf{r} \in \mathcal{H}$ and let $(\mathbf{x}_n)_{n \in \mathbb{N}}$ be the sequence generated by the following routine.

$$\begin{cases} \mathbf{y}_0 = \mathbf{r} \\ \mathbf{p}_0 = \mathbf{0} \\ \mathbf{q}_0 = \mathbf{0} \end{cases} \quad \text{and} \quad \begin{cases} \mathbf{x}_n = \text{prox}_{\mathbf{g}}(\mathbf{y}_n + \mathbf{q}_n) \\ \mathbf{q}_{n+1} = \mathbf{y}_n + \mathbf{q}_n - \mathbf{x}_n \\ \mathbf{y}_{n+1} = \text{prox}_{\mathbf{f}}(\mathbf{x}_n + \mathbf{p}_n) \\ \mathbf{p}_{n+1} = \mathbf{x}_n + \mathbf{p}_n - \mathbf{y}_{n+1}. \end{cases}$$

Then $\mathbf{x}_n \rightarrow \text{prox}_{\mathbf{f}+\mathbf{g}} \mathbf{r}$.

Proof highlights

- Set $\varphi: \mathbf{v} \mapsto \mathbf{f}^*(\mathbf{v} + \mathbf{r}) - \frac{1}{2}\|\mathbf{r}\|^2$ and $\psi = \mathbf{g}^{*\vee}$.
- Then $\text{prox}_{\varphi} \mathbf{v} = \mathbf{v} - \text{prox}_{\mathbf{f}}(\mathbf{v} + \mathbf{r})$ and $\text{prox}_{\psi} \mathbf{v} = \mathbf{v} + \text{prox}_{\mathbf{g}}(-\mathbf{v})$.
- Use Fenchel, some changes of variables, algebraic manipulations, and the proposition on the dual asymptotic behavior of the alternating prox algorithm.

Proof highlights

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- Use Fenchel, some changes of variables, algebraic manipulations, and the proposition on the dual asymptotic behavior of the alternating prox algorithm.

Remark

When $\mathbf{f} = \iota_{\mathbf{C}}$ and $\mathbf{g} = \iota_{\mathbf{D}}$ we do recover the Boyle/Dykstra theorem.

The prox of the sum of m convex functions

Proposition

Let $(f_i)_{1 \leq i \leq m}$ be functions in $\Gamma_0(\mathcal{H})$ such that $\bigcap_{i=1}^m \text{dom} f_i \neq \emptyset$. Set

$$f = \sum_{i=1}^m \omega_i f_i, \text{ where } \{\omega_i\}_{1 \leq i \leq m} \subset]0, 1[\text{ and } \sum_{i=1}^m \omega_i = 1.$$

Furthermore, let $r \in \mathcal{H}$ and set

$$\left[\begin{array}{l} x_0 = r \\ \text{For } i = 1, \dots, m \\ \quad \left[\begin{array}{l} z_{i,0} = x_0 \end{array} \right] \end{array} \right. \quad \text{and} \quad (\forall n \in \mathbb{N}) \quad \left[\begin{array}{l} \text{For } i = 1, \dots, m \\ \quad \left[\begin{array}{l} y_{i,n} = \text{prox}_{f_i} z_{i,n} \end{array} \right] \\ x_{n+1} = \sum_{i=1}^m \omega_i y_{i,n} \\ \text{For } i = 1, \dots, m \\ \quad \left[\begin{array}{l} z_{i,n+1} = x_{n+1} + z_{i,n} - y_{i,n} \end{array} \right] \end{array} \right.$$

Then $x_n \rightarrow \text{prox}_f r$.

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Then $x_n \rightarrow \text{prox}_f r$.

Remark

The above result provides a strongly convergent, qualification-free minimization algorithm for strongly convex problems.

Projecting onto the intersection of convex sets

Corollary (Gaffke/Mathar, 1989)

Let $(C_i)_{1 \leq i \leq m}$ be closed convex subsets of \mathcal{H} such that $C = \bigcap_{i=1}^m C_i \neq \emptyset$. Take $\{\omega_i\}_{1 \leq i \leq m} \subset]0, 1[$ such that $\sum_{i=1}^m \omega_i = 1$. Furthermore, let $r \in \mathcal{H}$ and set

$$\left[\begin{array}{l} x_0 = r \\ \text{For } i = 1, \dots, m \\ \quad \left[\begin{array}{l} z_{i,0} = x_0 \end{array} \right] \end{array} \right. \quad \text{and} \quad (\forall n \in \mathbb{N}) \quad \left[\begin{array}{l} \text{For } i = 1, \dots, m \\ \quad \left[\begin{array}{l} y_{i,n} = P_{C_i} z_{i,n} \\ x_{n+1} = \sum_{i=1}^m \omega_i y_{i,n} \\ \text{For } i = 1, \dots, m \\ \quad \left[\begin{array}{l} z_{i,n+1} = x_{n+1} + z_{i,n} - y_{i,n} \end{array} \right] \end{array} \right] \end{array} \right.$$

Then $x_n \rightarrow P_C r$.

Remark (Lapidus, 1980)

Suppose that the sets $(C_i)_{1 \leq i \leq m}$ are closed vector subspaces. Then the update rule reduces to $x_{n+1} = \sum_{i=1}^m \omega_i P_{C_i} x_n$. Hence, $(\sum_{i=1}^m \omega_i P_{C_i})^n \rightarrow P_C$.

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